SIESTA simulations of a power-recycled interferometer



Outline

SIESTA simulation of a power-recycled ITF:

- how the algorithm works
- validation / results
- another algorithm: ITF dynamics
- final considerations



SIESTA command OPitf

Outline:

- how the algorithm works
- validation / results
- another algorithm: ITF dynamics
- final considerations

SIESTA command **OPitf**:

- FFT simulation of a power-recycled interferometer
- computation of stationary fields inside the ITF
- solution searched by successive iterations



Power-recycled ITF

The same mechanisms used for a simple FP cavity are extended to a power-recycled ITF.

Basically, the ITF is treated as a set of three communicating cavities:

- North arm cavity
- West arm cavity
- central Michelson



Power-recycled ITF





1. Guess fields





2. Lock arm cavities





3. Solve arm cavities





4a. Lock power recycling





4b. Lock dark fringe





5. Solve central Michelson





Again and again



BORATOIRE MATÉRIAUX AVANCÉS

Start again!

- lock arm cavities
- solve arm cavities
- lock PR
- lock DF
- solve central itf

• ...

Outline:

- how the algorithm works
- validation / results
- another algorithm: ITF dynamics
- final considerations

Let's have a look at some results...

unless otherwise stated : grid 717mm, 256 points cavity adjustment @ every cycle pixel size = 2.8mm pixel size = 2.8mm



Virgo+



Virgo+ – no defects





Virgo+ – real RoC's



Virgo+ – real maps

Virgo+ – real maps & CHRoCC 3600m

Virgo+ – real maps & CHRoCC 3650m

Advanced Virgo

AdV – no defects

What about the sidebands?

Simulation of AdV with increasing losses in the central ITF (affected to the PRM)

BORATOIRE

on the average: CAR: 4 iterations SB: 6 iterations CPU time: 4.5 min

Outline:

- how the algorithm works
- validation / results
- another algorithm: ITF dynamics
- final considerations

OPglobal card:

- FFT simulation of a power-recycled interferometer
- computation of the temporal evolution of the fields inside the ITF ('dynamics')
- already presented in VIR-0563A-10, so I will not go into details
- slow but reliable method to validate other results!

OPglobal

Virgo+ with real mirror maps (extended to 330 mm)

Comparison: 'stationary' vs 'dynamic'

Virgo+ with real mirror maps (extended to 330 mm)

Outline:

- how the algorithm works
- validation / results
- another algorithm: ITF dynamics
- final considerations

Several things to do

Incomplete TODO list:

implement signal recycling

→ 'fast' algorithm for the central Michelson (should work in principle but it does not... hunt the bug!)

- → allow the use of transmission maps
- implement FFTW instead of the current FFT implementation

→ implement multithreading (for instance: carrier and sidebands on different threads)

→ whatever users want...

But most of all...

Some personal considerations:

SIESTA-FFT is a half-sleeping project (no pun intended):

1 developer (me) + 1 user (Romain).

I am leaving the collaboration in two weeks; Romain will finish his PhD ~ october 2012

It is big and heavy and slow to evolve, but I think still useful because:

- it tries to be as versatile as possible
- it integrates with the Virgo software environment (e.g. input/output in *frame* format)
- it can be easily run in `batch' mode via shell scripts
- the source code is open to everybody in the collaboration

However:

It <u>really</u> needs a boost:

• in the dreamworld, 1 developer 100% on SIESTA

• even more important: a user community (if nobody uses it, there is no reason to develop)

That's all folks

Thank you. Nice SIESTA to everybody.

Before addressing the algorithms for the power-recycled ITF, I will explain/remind how SIESTA works for a simple FP cavity. The very same mechanisms are applied to the ITF.

So, here is what SIESTA does for a FP cavity:

- 1) adjust the cavity to resonance
- compute the stationary field

adjust a FP cavity

solve a FP cavity

About the use of mirror maps

WARNING #1

Measured maps are about 900×900 pixels wide. Reducing map resolution is delicate, since it can significantly influence gain and losses.

After some tests, my conclusion is that the best practice is to reduce map resolution by averaging an integer number of neighbor pixels (e.g. averaging over 2×2 pixels, 4×4 , etc.).

This is what one gets for Virgo+ West cavity:

grid	grid	gain	losses	
(mm)	points		(ppm)	
717	2048	90.25	1004	no resampling of the maps
717	1024	90.24	1008	
717	512	90.21	1015	(why losses so high?
717	256	90.04	1054	see next slide)
717	128	89.89	1093	

About the use of mirror maps

WARNING #2

Why losses are so high?

 \rightarrow The maps have a diameter of 312 mm.

If we extend artificially the West map to 330 mm:

grid (mm)	grid points	diameter (mm)	gain	losses (ppm)
717	256	312	90.04	1004
717	256	330	92.09	583

Power-recycled ITF

SECOND POSSIBILITY: cavities adjusted only at the beginning

